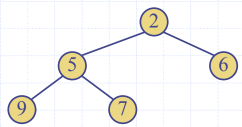
Heaps



Recall Priority Queue ADT (§ 7.1.3)

- A priority queue stores a collection of entries
- Each **entry** is a pair (key, value)
- Main methods of the Priority Queue ADT
  - insert(k, x) inserts an entry with key k and value x
  - removeMin() removes and returns the entry with smallest key
- Additional methods
  - min() returns, but does not remove, an entry with smallest key
  - size(), isEmpty()
- Applications:
  - Standby flyers
  - Auctions
  - Stock market

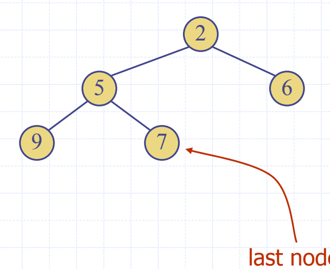
Recall Priority Queue Sorting (§ 7.1.4)

- We can use a priority queue to sort a set of comparable elements
  - Insert the elements with a series of insert operations
  - Remove the elements in sorted order with a series of removeMin operations
- The running time depends on the priority queue implementation:
  - Unsorted sequence gives selection-sort: O(n²) time
  - Sorted sequence gives insertion-sort: O(n²) time
- Can we do better?

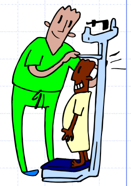
Algorithm *PQ-Sort(S, C)*
  Input sequence S, comparator C for the elements of S
  Output sequence S sorted in increasing order according to C
  $P \leftarrow$ priority queue with comparator C
  while $\neg S.isEmpty$ ()
    $e \leftarrow S.remove$ ($S.first$ ())
    $P.insertItem(e, e)$
  while $\neg P.isEmpty$()
    $e \leftarrow P.removeMin$()
    $S.insertLast(e)$

Heaps (§7.3)

- A heap is a binary tree storing keys at its nodes and satisfying the following properties:
  - Heap-Order: for every internal node v other than the root, $key(v) \geq key(parent(v))$
  - Complete Binary Tree: let h be the height of the heap
    - for $i = 0, \ldots, h-1$, there are 2^i nodes of depth i
    - at depth $h-1$, the internal nodes are to the left of the external nodes
- The last node of a heap is the rightmost node of depth h

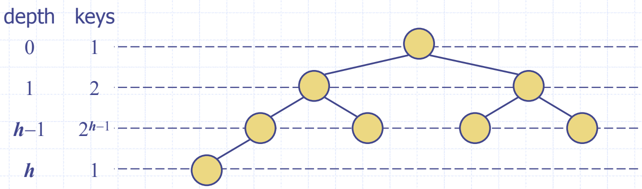


Height of a Heap (§ 7.3.1)



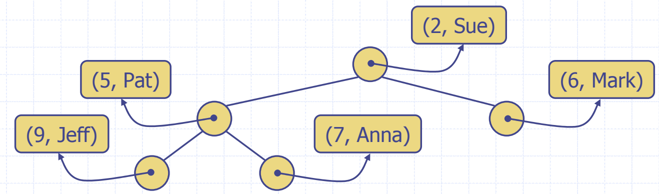
- Theorem: A heap storing n keys has height $O(\log n)$

  Proof: (we apply the complete binary tree property)
  - Let h be the height of a heap storing n keys
  - Since there are 2^i keys at depth $i = 0, \ldots, h-1$ and at least one key at depth h, we have $n \geq 1 + 2 + 4 + \ldots + 2^{h-1} + 1$
  - Thus, $n \geq 2^h$, i.e., $h \leq \log n$



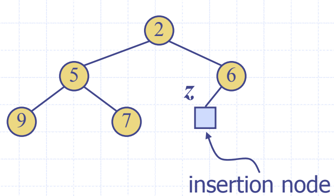
Heaps and Priority Queues

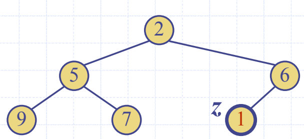
- We can use a heap to implement a priority queue
- We store a (key, element) item at each internal node
- We keep track of the position of the last node
- For simplicity, we show only the keys in the pictures



Insertion into a Heap (§ 7.3.3)

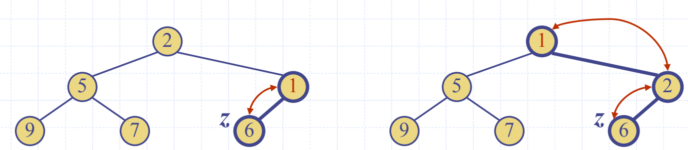
- Method insertItem of the priority queue ADT corresponds to the insertion of a key k to the heap
- The insertion algorithm consists of three steps
  - Find the insertion node z (the new last node)
  - Store k at z
  - Restore the heap-order property (discussed next)





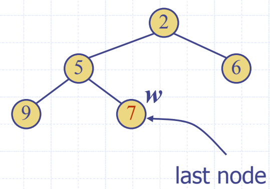
Upheap

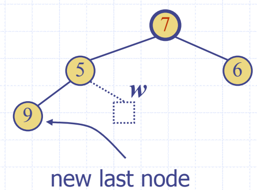
- After the insertion of a new key k, the heap-order property may be violated
- Algorithm upheap restores the heap-order property by swapping k along an upward path from the insertion node
- Upheap terminates when the key k reaches the root or a node whose parent has a key smaller than or equal to k
- Since a heap has height $O(\log n)$, upheap runs in $O(\log n)$ time



Removal from a Heap (§ 7.3.3)

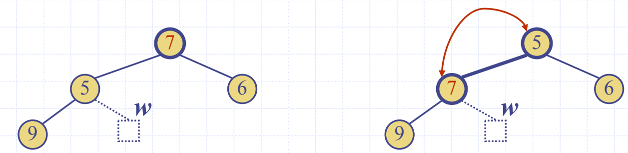
- Method removeMin of the priority queue ADT corresponds to the removal of the root key from the heap
- The removal algorithm consists of three steps
  - Replace the root key with the key of the last node w
  - Remove w
  - Restore the heap-order property (discussed next)





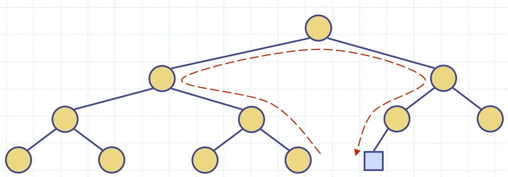
Downheap

- After replacing the root key with the key k of the last node, the heap-order property may be violated
- Algorithm downheap restores the heap-order property by swapping key k along a downward path from the root
- Upheap terminates when key k reaches a leaf or a node whose children have keys greater than or equal to k
- Since a heap has height $O(\log n)$, downheap runs in $O(\log n)$ time

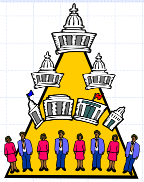


Updating the Last Node

- The insertion node can be found by traversing a path of $O(\log n)$ nodes
  - Go up until a left child or the root is reached
  - If a left child is reached, go to the right child
  - Go down left until a leaf is reached
- Similar algorithm for updating the last node after a removal



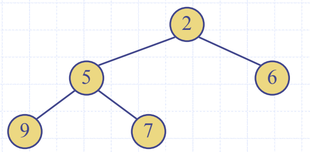
Heap-Sort (§2.4.4)



- Consider a priority queue with n items implemented by means of a heap
  - the space used is $O(n)$
  - methods insert and removeMin take $O(\log n)$ time
  - methods size, isEmpty, and min take time $O(1)$ time
- Using a heap based priority queue, we can sort a sequence of n elements in $O(n \log n)$ time
- The resulting algorithm is called heap sort
- Heap sort is much faster than quadratic sorting algorithms, such as insertion- sort and selection sort

Vector-based Heap Implementation (§2.4.3)

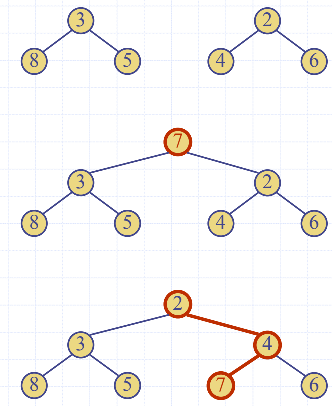
- We can represent a heap with n keys by means of a vector of length $n + 1$
- For the node at rank i
  - the left child is at rank $2i$
  - the right child is at rank $2i + 1$
- Links between nodes are not explicitly stored
- The cell of at rank 0 is not used
- Operation insert corresponds to inserting at rank $n + 1$
- Operation removeMin corresponds to removing at rank n
- Yields in-place heap-sort



	2	5	6	9	7
0	1	2	3	4	5

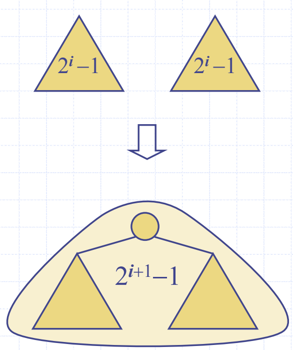
Merging Two Heaps

- We are given two two heaps and a key k
- We create a new heap with the root node storing k and with the two heaps as subtrees
- We perform downheap to restore the heap order property

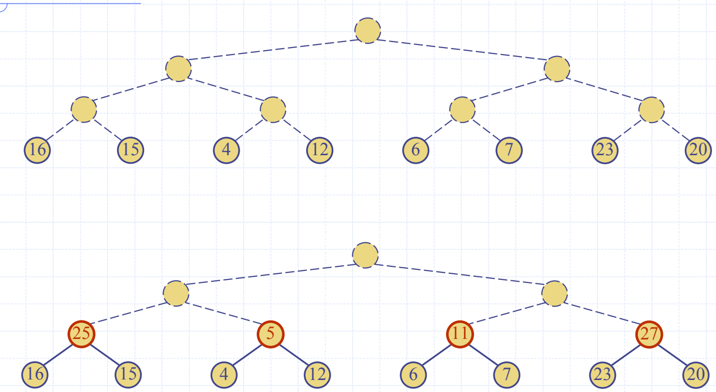


Bottom-up Heap Construction (§2.4.3)

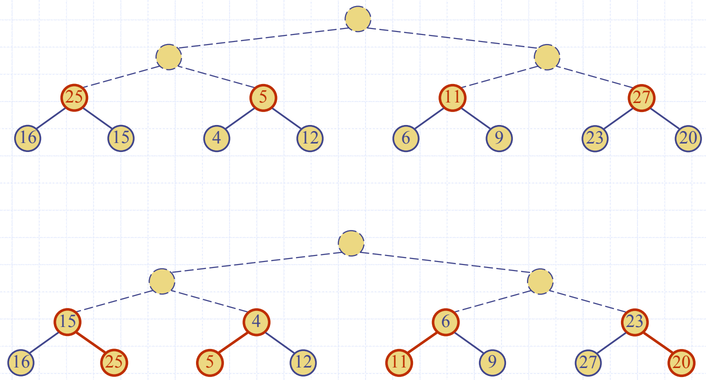
- We can construct a heap storing n given keys in using a bottom up construction with $\log n$ phases
- In phase i, pairs of heaps with $2^i - 1$ keys are merged into heaps with $2^{i+1} - 1$ keys



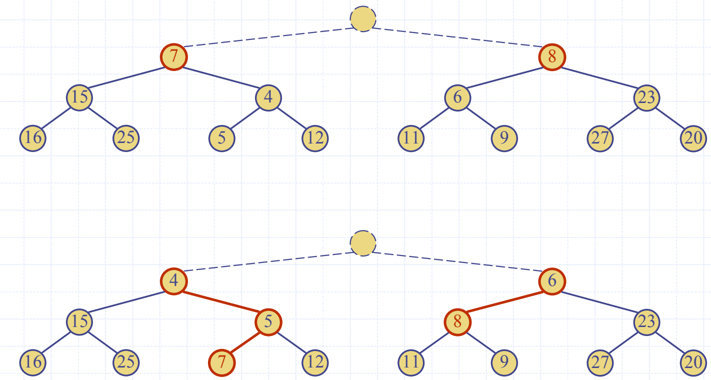
Example



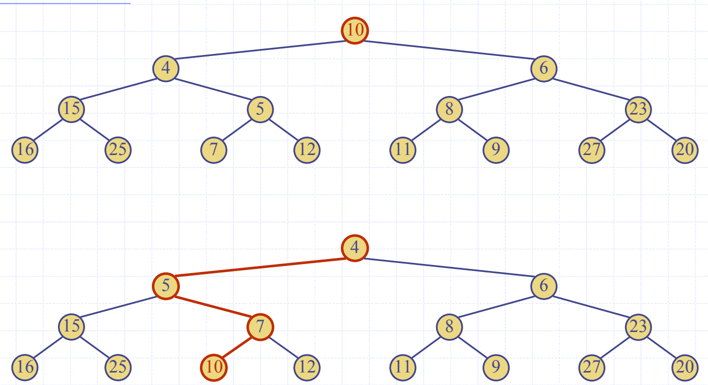
Example (contd.)



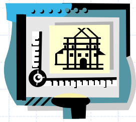
Example (contd.)



Example (end)



Analysis



- We visualize the worst-case time of a downheap with a proxy path that goes first right and then repeatedly goes left until the bottom of the heap (this path may differ from the actual downheap path)
- Since each node is traversed by at most two proxy paths, the total number of nodes of the proxy paths is $O(n)$
- Thus, bottom-up heap construction runs in $O(n)$ time
- Bottom-up heap construction is faster than n successive insertions and speeds up the first phase of heap-sort